

Review

Standardized precipitation measurements within ICOS: rain, snowfall and snow depth: a review

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Abstract. Precipitation is one of the most important abiotic variables related to plant growth. Using standardised measurements improves the comparability and quality of precipitation data as well as all other data within the Integrated Carbon Observation System network. Despite the spatial and temporal variation of some types of precipitation, a single point measurement satisfies the requirement as an ancillary variable for eddy covariance measurements. Here the term precipitation includes: rain, snowfall (liquid water equivalent) and snow depth, with the latter two being of interest only where occurring. Weighing gauges defined as Integrated Carbon Observation System standard with the capacity of continuously measuring liquid and solid precipitation are installed free-standing, away from obstacles obstructing rain or snowfall. In order to minimise wind-induced errors, gauges are shielded either naturally or artificially to reduce the adverse effect of wind speed on the measurements. Following standardised methods strengthens the compatibility and comparability of data with other standardised environmental observation networks while opening the possibility for synthesis studies of different precipitation measurement methodologies and types including a wide range of ecosystems and geolocations across Europe.

Keywords: ICOS, protocol, precipitation, rain, snow

INTRODUCTION

Precipitation is one of the most important abiotic variables related to vegetation survival, and growth and thus gross primary production. Accurate measurements of precipitation in its liquid and solid form are fundamental to acquire reliable knowledge on all facets of the hydrological cycle, representing a key component in ecosystem understanding and hydro-meteorological and climate models. As a pan-European research infrastructure the Integrated Carbon Observation System (ICOS) is providing long-time series of harmonised and high-precision data, including data on carbon cycle, greenhouse gas budget and further associated meteorological variables including precipitation. Precipitation may interfere with other measurements such as radiation and eddy flux measurements as the accuracy of sonic anemometers and open-path gas analysers decline under heavy rain or snowfall with the timing and intensity of precipitation being valuable indicators as part of the data quality control procedure.

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ited from air onto the ground. The main products are: rain, drizzle, hail, dew, fog and snow. The total amount of precipitation reaching the surface is expressed in terms of the vertical depth of water (or what would be obtained by melting the snow cover – referred to as snow water equivalent SWE) covering a horizontal surface. Whereas liquid precipitation is represented by rainfall, solid precipitation is understood as snow, ice, sleet and hail. Snowfall is regarded as the accumulation of fresh snow since the last observation, while snow depth is the total depth of snow including fresh snow and the already existing snow on the ground.

In addition to these precipitation types one has to distinguish between various precipitation components: throughfall, defined as the precipitation that passes directly through a plant canopy, and stemflow, classified as the precipitation that drains from leaves, branches and twigs down along the stems of plants. Together they are classified as below-canopy precipitation. An excellent review is given in Levia and Frost (2003) and Levia *et al.* (2011). Lack of solid or liquid precipitation does not exclude the presence of dew or fog, as dew is water vapour that has condensed onto a surface, while fog is composed of tiny liquid water droplets suspended in the air.

The unit of precipitation is linear depth, usually provided in mm (volume/area) for liquid precipitation, while snow depth is measured in cm (Table 1). Less than 0.2 cm of snow is generally called a trace. The depth of snow on the ground is measured daily in whole cm according to the WMO, but high resolution measurements are possible with optical sensors and the use of simple cameras.

The spatial variability of liquid and solid precipitation is dependent on the latitudinal and altitudinal location together with the local topography that has an effect on particular types of precipitation, but also affected by local and regional weather patterns. Depending on type, precipitation events can last from a few minutes to prolonged periods of time. In Nordic and alpine/high altitudinal regions, snowfall and snow cover can last several months and occur anytime throughout the year.

Table 1. Measured variables and standard units within ICO	S
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Variable	ICOS unit
Rainfall	mm
Snowfall	mm
Snow depth	cm
Throughfall	mm
Stemflow	mm
Dew	kg m ⁻² or mm m ⁻² (nearest tenth of a mm)
Fog	1 m ⁻²

WMO (2010) standards on how and where to measure precipitation, provide means for analysing the local conditions at ICOS ecosystem stations in relation to climatological standards and spatial distribution of precipitation based on existing WMO-stations in the region. Furthermore, available long-time series are useful for temporal analysis (extremes, frequencies, sequences, etc.). Even with respect to the high spatial and temporal variability of some types of precipitation (convective type) relative to the area of interest (eddy covariance (EC) system footprint), a single point measurement satisfies the requirement as an ancillary variable for EC measurements within ICOS. The objectives of this paper are to provide the guidelines required to describe and report the amount of liquid and solid (where applicable) precipitation accounted for in a standardised manner at each ICOS ecosystem station.

METHODOLOGY

At ICOS ecosystem stations precipitation is measured in liquid and solid form: rain, sleet, graupel, hail, snowfall (SWE) together with the total accumulated snow (snow depth), where occurring. All but snow depth are predominantly measured with precipitation gauges (rain gauge if only liquid precipitation is measured). Precipitation measurements represent point measurements and are representative to a limited area, accompanied by errors and are very sensitive to exposure, and in particular to wind (Sevruk and Nespor, 1994; Groisman *et al.*, 1999; WMO, 2010; Wolff *et al.*, 2015; Kochendorfer *et al.*, 2017a,b). Fog, dew, throughfall and stemflow are facultative measurements within ICOS at the moment, and therefore only briefly outlined in the section dealing with potential improvements in the future.

Rain and snow water content measurements: methodology and instrumentation

Precipitation gauges are the most common instruments used to measure liquid and solid precipitation. It has been agreed within the frame of ICOS that WMO recommendations and guidelines are to be followed where possible (instrumentation and installation location) or adapted accordingly. Regarding precipitation gauges, there are more than 50 different types (Frumau et al., 2006; Nitu and Wong, 2010) being used in the world. The most commonly used precipitation gauge recognised by the WMO (1984, 1989, 2010); Sevruk et al. (2009), Vuerich et al. (2009) consists of a funnel leading into a container where the accumulated water and melted snow are stored between observations. Two of the WMO (1984, 1989, 2008, 2010) standards are the weighing-recording type and the tippingbucket type. The weighing-recording precipitation gauge has the capacity of measuring liquid (rain) as well as solid (hail and snow) precipitation, while the common tipping bucket rain gauge is only limited to measure rainfall.

The weighing-recording gauge was defined as ICOS standard, whereas the tipping-bucket rain gauge can only be used as additional sensor or as part of the backup meteorological station. The underlying principle of weighing-recording gauges is the continuous recording of the weight of a container, together with the precipitation accumulated therein. Examples for such gauges are the OTT Pluvio² (Pluvio series, OTT Hydromet, 2014) or the Geonor T-200B series (Geonor, Inc., 2016) (detailed information available from the manufacturers). The principle underlying tipping-bucket rain gauges is the collection of water in a container, divided into two compartments (buckets) balanced in unstable equilibrium about a horizontal axis. Although their application is simple and they are widely used, tipping-bucket rain gauges are not only accompanied by the same error sources (see respective section) as the weighing gauges but also suffer from additional sampling errors induced by tipping action in heavy rain. Moreover, the exact onset or end of precipitation events cannot be determined. Low intensity rain events (drizzle) can occur over a prolonged period of time before 0.2 mm have been accumulated and registered by the tipping bucket. Additionally, random tipping of the gauge leads to misreading of a rain event, its timing and its intensity. Though tipping bucket rain gauges have the possibility to be heated, they are not recommended for winter conditions. The reason for this is the delay in measuring snowfall or better snow water equivalent (possible delay of several hours). The longest delays should be expected for low density snow at very cold air temperatures. While out of point of view of biological effects (water availability), time resolution of precipitation measurements might not need to be very high, at the same time the momentary rain intensity affects water flow into the ground (surface flow vs. drainage) and so to some extent subsequently evaporation. As a consequence, tipping buckets are not compliant with ICOS standards.

In addition to these two measurement principles, optical precipitation sensors are used at many flux measurement sites and certainly at meteorological observation sites around the world. The WMO Commission for Instruments and Methods of Observation (CIMO) (Nitu and Wong, 2010) identified the following three types of optical measurements: (1) Sensor operating on the principle that a partially coherent infrared or visible light beam, when passed through an irregular medium, will have an altered frequency. In other words, when precipitation falls through an infrared beam it introduces frequencies in the beam that are a function of the size and speed of the particle. (2) Sensor measuring the extinction caused by the particle falling through a thin light sheet determining the size and velocity of the droplet from the amplitude and duration of the light extinction. (3) Instrument measuring the forward optical scattering by the particles and the water content of the precipitation using a rain sensor. Precipitation intensities

that are estimated from forward optical scattering and from the rain sensor jointly with an air temperature measurement allow for the identification of precipitation types (liquid or solid), amount, and intensity (Nitu and Wong, 2010).

Although it is expected that optical instruments perform better than weighing gauges because of their advanced technological features, they generally suffer from lower accuracy. In contrast, they do not suffer from errors applicable to the collecting/recording precipitation gauges, and have the ability to measure individual droplet size and number. Nevertheless, they have the tendency to overestimate precipitation (e.g. Lanzinger et al., 2006; Lanza et al., 2010; Liu et al. 2013). One explanation of such a limitation is that two (or more) coincident particles in the light sheet can appear as one large particle (Lanzinger et al., 2006). On the other hand Liu et al. (2013) suggest that small raindrops tend to be omitted in larger size raindrops due to shadow effects of light. Furthermore, optical instruments are sensitive to orientation in regards to the prevailing wind direction as wind shading can possibly compromise the measurements. In addition, splashing effect of large raindrops off the sensor housing into the measurement volume contributes further to the uncertainty of such optical precipitation sensors. For these reasons the instruments are not compliant for precipitation measurements in ICOS. They can be used only if no appropriate location for the weighing gauge can be found or as additional sensors.

Measuring snow depth is mandatory in ICOS where snow occurs and can be done either automatically or manually (snow stake), depending on the frequency and intensity of snowfall at the site. The majority of the ultrasonic type snow depth sensors, e.g. SR50/SR50A Sonic Ranging Sensor (Campbell Sci., 2011), USH-8 Ultrasonic snow depth sensor (Sommer Messtechnik, 2015), 260-700 Ultrasonic Snow Depth Sensor (NovaLynx, 2015) are also known as sonic ranging depth sensors. Thereby the sensor determines the distance from the transmitter to the target (snow surface) by emitting ultrasonic pulses and listening to the returning echoes that are reflected by the target. The distance is deduced from the transmission time between the emission and the reception of the echo. The sensor detects the increase in snow depth after snowfall and the decrease during melting periods.

At sites that experience snow less frequent or for a few days a year only, a semi-automatic approach like digital (web) cameras pointing at a permanent fixed snow stake or a fully-manual approach measuring snow depth by means of a snow stick can be used. These two methods can be applied also in addition to the sonic sensor to further improve the information on snow cover distribution during *e.g.* snowmelt periods or in particular areas (*e.g.* below canopy).

Snow depth measurements are taken as long as there is snow on the ground. If half the exposed ground is without any snow and other areas are covered with snow, then snow depth is reported as the average between the measured snow depth and the bare ground (WMO, 2008). Snow depth measurements should always be taken close to the precipitation gauge.

Sources of error for precipitation gauges

All types of precipitation measurements at ICOS ecosystem stations are done with the aim to provide long-term high-quality continuous data. Precipitation gauges are accompanied by errors induced due to wind effects (systematic wind field deformation above the gauge orifice) (Wolff et al., 2013; Colli, 2014) and the inhomogeneity introduced by the design of the measuring device (Sevruk and Nespor, 1994). Further errors include wetting losses (Sevruk, 1974a) and evaporation losses (Sevruk, 1974b; Leeper and Kochendorfer, 2015) inside the collection funnel, sampling errors due to weighing and tipping mechanisms (Sevruk and Chvíla, 2005) and in- and out-splashing effects due to device location, as well as random observational and instrumental errors. These errors and limitations have been recognised by the WMO (1984; 2008; 2010 and, specifically for snow, 1998) and were highlighted in comparison studies carried out over the past decades (e.g. Fruman et al., 2006; Sevruk et al., 2009; Wolff et al., 2015; Buisán et al., 2017). The systematic error of solid precipitation measurements is commonly large as the results from the recent Solid Precipitation Intercomparison Experiment (SPICE) have shown (Rha et al., 2014; Wolff et al., 2013, 2015; Buisán et al., 2017; Kochendorfer et al., 2017a,b). Wind speed is the most important environmental factor contributing to the under-catchment of solid precipitation as low wind speeds of 1.5 m s⁻¹ already cause a loss of 30% in precipitation recorded with unshielded precipitation gauges and with increasing losses at higher wind speeds (Wolff et al., 2015). That said, studies by Buisán et al. (2017) and Kochendorfer et al. (2017a) point out that wind-shielded gauges show a lower bias than unshielded gauges.

Gauges are shielded either naturally (for example, forest clearing, hedges) or artificially to minimise the adverse effect of wind speed on these measurements (Sevruk et al., 2009; Nitu and Wong, 2010; Rasmussen et al., 2012). The type of windshield configuration, as well as gauge type, will alter the relationship between wind speeds and catch efficiency, and have implications on data homogeneity. Though the Tretyakov wind shield is a standard WMO recognised wind shield, for example, it has been shown not to be applicable in winter conditions as it is causing snow to accumulate and to enter the precipitation collector in windy conditions. The Alter wind shield (Alter, 1937; WMO, 2012), that is composed of loose hanging lamellas without collecting snow, has been recommended by several Institutes, including the Finnish Meteorological Institute (pers. communication) and is thus ICOS standard. Although the standard off-the-shelf shield is connected to

the post of the gauge, it is strongly recommended that the shield is mounted independently of the post of the gauge to reduce the impact of wind vibration on the instrument.

Instrument setup

The geographical reach of ICOS ecosystem stations currently expands from Southern Europe to North of the Arctic circle. The network further includes stations in French Guiana. While some ICOS ecosystem stations experience precipitation in liquid form only, other stations are experiencing also solid precipitation during the winter and occasionally during the summer months. Standardised precipitation measurements therefore should consider this variability, delivering the most representative, accurate, reliable, and qualitatively best data possible.

WMO guidelines include information regarding the maximum terrain slope, description of obstacles and the minimum distance of obstacles as function of their height. Furthermore, the WMO (2010) handbook recommends positioning precipitation gauges in an area with homogeneous and dense vegetation of the same height as the gauge orifice, or alternatively by simulating the effect of vegetation through the use of appropriate fence structures or the application of windshields around the gauge. That said, there are no strict rules on exact orifice height (most commonly used height varies between 0.5 and 1.5 m according to WMO, 1989), providing some flexibility and pointing towards the need of caution for sites with differing snow cover heights.

In ICOS, it has been decided that no precipitation measurements using a weighing gauge or tipping bucket are carried out on top of the tower, nor along the tower itself. Reasons for such a decision are wind and tower induced vibrations, obstruction through the tower itself as well as wind distortion induced errors. In case no appropriate open space is found near forest sites that fulfil the above properties, then the installation of an optical instrument on top of the tower is admissible as an exception.

Snow depth sensors are installed according to the instrument (model) manual at 1.5-2 m above ground (covered with artificial grass or other surface depending on instrument guidelines). At stations where a fixed snow stake and a digital camera are used, care has to be taken in orientating and installing (field of view of camera towards North to avoid glare) these providing visible and clear images of the snow stake and the snow depth reading. Furthermore, snow stakes have a metric gauge well visible to the human eye. Images are taken several times a day during daylight hours (or throughout the night if infrared (IR) light/camera is available). Implementing digital images at sites provides additional information on snow cover distribution during snowmelt season.

The nearest WMO standard or official station measuring precipitation is used as a reference station, and own measured values regularly compared and verified. Systematic discrepancies, such as consistently lower or higher readings over a prolonged period of time (be it months), are indicative of misplacement of instrument, over- or under-estimation or other random errors.

Spatial and temporal sampling design

Locations of gauges are chosen in places as open as possible and not further than the maximum allowed distance of 1 km from the EC tower away where precipitation can be measured according to the site requirements outlined above. Regarding snow depth, the measurement point is away from roofs, depressions, trees and snow dumping areas at all sites that encounter snowfall during winter months. Furthermore, these measurements are carried out in locations away from areas that are influenced by local turbulence snowdrifts but close to the precipitation gauge to represent roughly the same "collection" area (relevant to water storage in snow and water balance studies in the spring), but not obstructed herewith. Snow depth measurements below the forest canopy are undertaken using a fixed snow stake and a digital camera in locations where soil temperature and soil moisture are measured.

The minimum acquisition frequency for continuous measurements of precipitation and snow depth is 0.017 Hz (one measurement every 60 s). Depending on site setup, precipitation data can be automatically sampled at 10 s resolution and integrated over 1 min. With it, averaging fluctuations or noise caused by the vibrations of the weighing gauge mechanisms/wind pumping (Sevruk and Chvíla, 2005; WMO, 2010) are automatically removed. Nevertheless, high-resolution data output by weighing gauges offers further the possibility of investigating rain intensity of short intensive rain showers. Automatic snow depth measurements are recorded as 30-min average values. At sites that experience snow only a few days per year, manual measurements are feasible and carried out once a day at a fixed time. When using a fixed snow stake and digital camera, pictures have to be taken several times a day during daylight hours or throughout the night if an IR camera or IR light is available. Images must be taken at minimum every four hours, starting at midnight.

Calibration and maintenance

Calibration of weighing precipitation gauges commonly involves the use of a series of weights (50, 100, 500, and 1000 g) or by adding known amounts of water (50, 100, 500, and 1000 ml), which, when placed in the bucket or catchment container, provide a predetermined value equivalent to a specific amount of precipitation. Calibration is done twice a year following manufacturer's guidelines. Due to the impracticability of removing some precipitation gauges (typically mounted on a concrete grounding) calibration (and checks) can be carried out on a dry and calm day, before and after the winter season, when the collection container will be cleaned and filled with an exact known amount of antifreeze liquid (to melt and to avoid further freezing of precipitation) or a known amount of oil, in order to avoid evaporation loss during the summer season, respectively.

Sonic snow depth sensor calibration checks are done at least in the beginning and end of the snow season using a measuring stick. Additional checks during the season are recommended. Annual replacement of desiccant is also required. Cameras do not need calibrations, but are checked and cleaned on a regular basis in order to avoid accumulation of snow and ice on them. The lens and its focus are checked and cleaned prior to the winter or before the first snow is expected in order to avoid miss-orientated and blurry images and thus loss of information. Images and algorithms are frequently checked in order to guarantee an accurate snow depth reading where site instruments are not being checked and supervised on a daily basis.

Occasionally instruments need to be replaced depending on exact use, material degradation, sensor drift, manufacturer guidelines, instruments taken down for service or calibration, lightning strike, damage caused by other natural forces (storm) or animals, mechanical damage or due to sensor malfunction. Is a replacement needed (not when replacement takes place due to instrument malfunction), then if possible the new sensor should be operated at least for a period of one month alongside the existing one in order to capture a variety of precipitation events and intensities. In order to guarantee on-going measurement, replacement instruments are recommended to be purchased well in advance so that alongside comparison measurements can be made possible. Such comparisons are necessary for sensor drift correction calculations.

Auxiliary measurements

Another method in verifying precipitation events is the use of leaf/surface wetness sensors. They enable verifying whether or not a precipitation event has occurred should the gauge show anomalous readings or values. They also provide non-quantitative information on the occurrence of fog and dew, both of which are relevant variables for canopy and hydrological processes (canopy conductance, vapour pressure deficit, etc.). These wetness sensors are resistor type sensors. When fog, dew or raindrops hit the wetness sensor surface, a contact is made between electrodes and a relay is cut through. There are different types of surface/ leaf wetness sensors, some simple ones that only indicate existence of water on the sensor surface, e.g. the Skye surface wetness sensor (SKYE - SKLW 1900; Skye, 2007) and the Campbell Sci. - 237-L Leaf Wetness Sensor (Campbell Sci., 2010), or other more sophisticated ones, such as the Decagon Dielectric Leaf Wetness Sensor (Decagon - LWS; Decagon, 2016, now distributed by METER ENVIROMENT (METER Group, 2018)). Depending on the dielectric constant this LWS differentiates between different types of deposition. For example, ice has a much lower dielectric constant than liquid water, so the sensor output from frost is much lower than that from a similar amount of rain or dew.

Wind speed and ambient air temperature measurements are part of the standard measurement suite at ICOS ecosystem stations with both variables measured as part of the eddy covariance setup and in addition as part of a backup meteorological station. Air temperature and wind speed measurements (carried out at the orifice rim height or derived from higher located wind speed values) are used in wind-induced error correction procedures (Wolff *et al.*, 2015 and Kochendorfer *et al.*, 2017a,b).

Data quality control and calculations

This section describes data quality procedures and calculations needed to obtain the final 30-min total precipitation values from the raw output signal of the sensors. It is recommended for these to be carried out according to the specific instrument guidelines, algorithms and measurement recommendations therein.

Weighing gauges are sophisticated precipitation gauges and particular algorithms for accurate calculations must be applied to the raw measurements. As an example, the algorithm to calculate the precipitation during a specified period (30-min) is based on input data of one-minute mean values (10 s scan). The signal value from the vibrating strings (Hz) is already converted to mm (bucket weight). The algorithm then sequentially checks the every-minute values to find the lowest value after the highest is reached but not lower than the already approved corrected value from the previous period. The difference between the end and the start value then equals the amount of precipitation (change in bucket weight). By this, the algorithm corrects for eventual evaporation losses and the effect of gauge evaporation becomes negligible. The algorithm also filters out noise and checks for sudden excessive amounts, which may be correct if heating has been turned on and caused melting of ice that has recently fallen into the bucket, and are discarded otherwise. A wider range of quality control procedures are described in Reverdin et al. (2016) including a detailed flagging and work flow system and summarised in Kochendorfer et al. (2017a,b) but with emphasis on solid precipitation. Additional procedures that are applicable to all forms of precipitation are manual quality control measures, such as removal of data due to maintenance, bird droppings or other deposits (leaves or needles in forest ecosystems). Since wetness sensors are accompanying precipitation measurements their readings can be incorporated in quality control procedures as well.

Wind-induced errors can attribute up to 80% error/ loss at high wind speeds (Wolff *et al.*, 2015; Buisán *et al.*, 2017) leading to an under-catch of true solid precipitation during winter months. This high loss is attributed to the fall velocity and size of snowflakes that get diverted around precipitation gauges in high winds. Wolff *et al.* (2015) investigated changes in catch ratio (using 10-min running means and 60-min values) under various temperature scenarios and showed that for air temperatures above 2°C, where precipitation is mainly falling as rain, the catch was not significantly influenced by wind (data incorporated in the study originated from winter data only). Nevertheless, Wolff et al. (2015) recommend no wind corrections for temperatures above 3°C until further studies on summer precipitation are available. The algorithm developed by Wolff et al. (2015) has been simplified and introduced in Kochendorfer et al. (2017a,b) and is applicable to 30-min values and therefore implementable in ICOS data processing procedures. That said, this correction is applicable to data recorded using -2°C as a filtering threshold for solid precipitation. Implementation of the Kochendorfer et al. corrections requires air temperature and wind speed measurements at orifice rim height. For sites without such measurements potential wind speed can be determined based on the log wind profiles (Thom, 1975). Such vertical profile estimations are site specific though (use of roughness length, displacement height, etc.) and require further evaluations at sites with existing wind profile measurements.

Snow depth readings are required to be done to an accuracy of 1 cm, as recommended by the WMO (2008) guidelines. Snow depth values extracted from digital camera images are inspected and compared to manual readings carried out as frequently as possible and in particular at manned stations. There, manual readings are done on a daily basis so corrections and possible post processing of images, conducted by the Ecosystem Thematic Centre (ETC), and their verification and improvement of the image processing algorithm is possible.

Final dataset

Data originated from the precipitation gauge measuring rain and snowfall are submitted by the ecosystem stations to the ETC at the frequency rate they were collected with quality control, calculations and corrections applied by the ETC. Is an optical snow depth device used at the site, 30-min average snow depth values are submitted. Images taken at an interval of four hours starting at midnight are also submitted to the ETC. The final dataset is then delivered as 30-min averages/totals along with accumulated amount of precipitation by the ETC. In addition to the actual precipitation measurements metadata included in Table 2 are submitted to the ETC and updated accordingly.

Potential improvements in the future

Some national station networks apply to some of their precipitation data products post-corrections for windinduced undercatch and other systematic errors like evaporation from funnels of tipping gauges. However, little is known yet about required adaptations of such corrections to the measurement set-up mandatory in ICOS,

Metadata precipitation gauge	Metadata snow depth
Instrument model and serial number	Instrument model and serial number (sonic sensor)
Instrument specific calibration coefficients	Instrument specific calibration coefficients (if applicable)
Collection height above ground	Measurement height (sonic sensor) above ground
Location and distance of precipitation gauge from flux station	Location and distance of sonic sensor from flux station
Date of calibration (twice a year)	Date of sonic sensor calibration (if appl. twice a year)
Date of instrument replacement (if applicable)	Date of sonic sensor replacement (if applicable)
Name of nearest WMO reference station	Name of nearest WMO reference station
Distance to nearest WMO reference station	Distance to nearest WMO reference station
Coordinates of nearest WMO reference station	Coordinates of nearest WMO reference station
Instrument used at the nearest WMO reference station	Instrument used at the nearest WMO reference station
Correlation coefficient between in situ data and ref station	Correlation coefficient between in situ data and ref station
Wind shielding method	Size of field of view of optical sensor
Location and surface wetness sensor model used	Camera model and serial number (if applicable)
	Image format (if applicable)
	Timestamp of images (UTC, local, etc.)
	Distance of snow stake from flux site
	Distance of camera from snow stake
	Time of day of manual measurement (if applicable)

Table 2. The following metadata should be provided in addition to the actual measurements

which aims at minimizing the underlying errors. All types of precipitation gauges (catching and non-catching) suffer from accuracy issues. A tipping bucket might have a measurement accuracy of 2% but has the highest sampling error (timing, random tipping, and delayed reporting when heated in the winter). Optical (non-catching) devices have the lowest measurement accuracy regarding precipitation amount but require the least maintenance. Weighing gauges have high measurement accuracy (0.1%), perform well when shielded under both summer and winter conditions, and do not exhibit readings since they measure precipitation as it falls. It is clear that, in order to achieve data compatibility when using different precipitation gauge types and shielding during all weather conditions, corrections to the actual measurements are necessary. In all cases where precipitation measurements are adjusted in an attempt to reduce errors, it is necessary that both, the measured and adjusted values, be published as part of the metadata. For the future, it is recommended to use additional measurements at ICOS ecosystem stations, such as e.g. lysimeters, to collect evidence for possible future parameterisations of such a correction. A brief overview of existing approaches is given in the following.

Wagner (2009) summarised corrections (wind, wetting and evaporation loss; operational errors, *etc.*) applicable to precipitation gauges for the Bavarian Forest administration, Germany. These methods are described in detail in Richter (1995); Sevruk (2004) and WMO (2008). The Richter (1995) correction, which is used by the German Weather Service (DWD) not in general but for hydrometeorology products, does not explicitly include wind speed as a predictor variable since the rain gauge network has a higher density than the weather station network, leaving many rain gauges without wind speed data. This might introduce uncertainty into the precision of daily time series when comparing *e.g.* windy to calm days, but the resulting long-term sums would be less affected and led *e.g.* to a good catchment water budget closure in a case study at the ICOS Associated Candidate station Wüstebach (Graf *et al.*, 2014). Typically, the Richter (1995) correction is applied to daily sums and consists of a single non-linear equation with two parameters that depend on precipitation type and site geometry:

$$P_{corr} = P_{raw} + b P_{raw}^{c}$$

with: P_{corr} the corrected daily precipitation sum (mm), P_{raw} the measured daily precipitation sum, *b* and *c* correction parameters which depend on precipitation type and mean horizon elevation angle. Typical values for *c* and b range between 0.4 to 0.8 and 0.2 to 0.7, respectively. The largest corrections are applied for snow, such that it is also an option to correct only solid precipitation.

Applying transfer functions in order to correct undercatch of solid precipitation at sites where wind speed is not measured at orifice rim height require estimated velocity values from log wind profile measurements (together with site specific roughness length and zero plane displacement height values). Such estimates introduce further uncertainties, that can be tested at sites where wind speed is measured simultaneously at different heights and representative for correction and wind profile evaluation.

ICOS is a network including a wide range of ecosystems with different climatic properties. It is suggested to carry out validation/synthesis studies including sites that have independent measurements of rain, *e.g.* optical instruments, lysimeter or catchment budget measurements.

Further significant precipitation measurements

There are several measurements relevant to the hydrological cycle and hydrological modelling, which are not required, but recommended within the ICOS portfolio. These are below-canopy precipitation in forests as well as fog and dew. There is no classification of below-canopy precipitation done by the WMO, nor is there a standardised method for such measurements yet. As the name throughfall suggests, its collection is proving to be very complex with a small-scale representation. Furthermore, a reliable collection system does require many collection points to deliver a representative estimation of the actual throughfall amount. Depending on vegetation type, density and time of year throughfall amount can be up to 100% of the bulk precipitation. The most commonly used measurement method involves manual precipitation gauges set out in a random distribution along the forest floor, which require tens of gauges to become representative (Hansen, 1996; Levia and Frost, 2003; Keim et al., 2005; Fruman et al., 2006). Other methods involve individual throughfall gutters connected to precipitation gauges and set up in such a way that the water is draining off centrally into a precipitation gauge. Gauge types span from simple home-made low-cost gutters and gauges to sophisticated stainless steel gutters and recording precipitation gauges (Fig. 1).

Similarily to the throughfall, there are no standardised methods available for stemflow. Measurements of stemflow might be negligible in species such as spruce or pine trees where the surface of the bark is too rough to allow a significant flow. Contrary at a beech site it was observed that even 15 mm precipitation was sufficient to create more than 100 l stem flow on an individual tree (Spank, 2010). Stemflow is mainly collected from forest trees using flexible silicon tubing that is cut longitudinally and wrapped, or polyurethane foam modelled in an upward spiral around the tree trunk (Levia and Frost, 2003; Spank, 2010). Water is then drained into a storage tank equipped with a pressure sensor to measure the filling level (Fig. 2).

Unlike rainfall, both fog and dew depositions strongly depend on local properties of the site itself. Large amounts of fog precipitation have been found *e.g.* in cloud forests on Atlantic Islands in the vicinity of Europe, where cloud water is intercepted by trees and then drips onto the surface (*e.g.* Aboal *et al.*, 2000). Fog can contribute excessively to



Fig. 2. Automated stemflow collector at the BULB (Beech Stand Landberg) beech site, TU Dresden, Germany.



Fig. 1. Examples of throughfall collectors. The centrally collected throughfall collection system and an additional Hellmann precipitation gauge at the Anchor Station Tharandt (spruce site), TU Dresden, Germany.

the water balance of an ecosystem and can be measured with various methods. According to the WMO (2010) the most widely used fog-measuring instrument consists of a vertical wire mesh cylinder which is centrally fixed on the top of a precipitation gauge in such a way that it is fully exposed to the free flow of the air.

The amount of dew depends on the physical properties of the collection surface, size, orientation and inclination. A theoretical upper limit is given by the heat removal enabled by nocturnal net radiation. This leads to values considerably below 1 mm per night, in good agreement with measured maxima around 0.5 mm (Monteith, 1963; Häckel, 1999; Graf *et al.*, 2008). For the amount of dew, various automated weighing gauges/microlysimeters have been developed (*e.g.* Heusinkveld, 2006; Graf *et al.*, 2008; Ucles *et al.*, 2013; Price and Clark, 2014).

Regarding below canopy snow depth an alternative method is the installation of an optical sensor along a motorised transect. Hereby an optical sensor drives along a transect below the canopy giving a rather detailed distribution of snow depth along the forest floor, a method that is more representative than a manual single point measurement. Further methods are laser scanners scanning the snow surface in several points and outputting an average of the respective snow depth. A forth method or option is the installation of several digital cameras and snow stakes.

CONCLUSIONS

1. Precipitation is one of the most important abiotic variables related to vegetation growth. Moreover, it is fundamental to acquire reliable knowledge on all facets of the hydrological cycle. These measurements provide further a basis for climate classification as standardised measurements across Integrated Carbon Observation System ecosystem stations improve comparability and quality of the data.

2. It has been decided to implement weighing gauges, together with the classical Alter wind shield as the standard total precipitation gauge across ICOS ecosystem stations, while automatic snow depth measurements are mandatory at sites where regular prolonged snow cover occurs during winter months. Sites that rarely experience snowfall do manual measurements as long as there is snow on the ground.

3. Using the WMO standardisation, where possible, on how and where to measure provides means for analysing local and regional conditions in relation to climatological standards and nearby existing WMO-stations. Furthermore, following such standardized methods strengthens the compatibility and comparability of data collected by the ICOS network with other standardised environmental observation networks in the world. 4. A standardisation across all ICOS ecosystem stations opens up the possibility for synthesis studies of different precipitation measurement methodologies and types including a wide range of ecosystems and geolocations in Europe.

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